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Secure System Composition and Type Checking using Cryptographic Proofs

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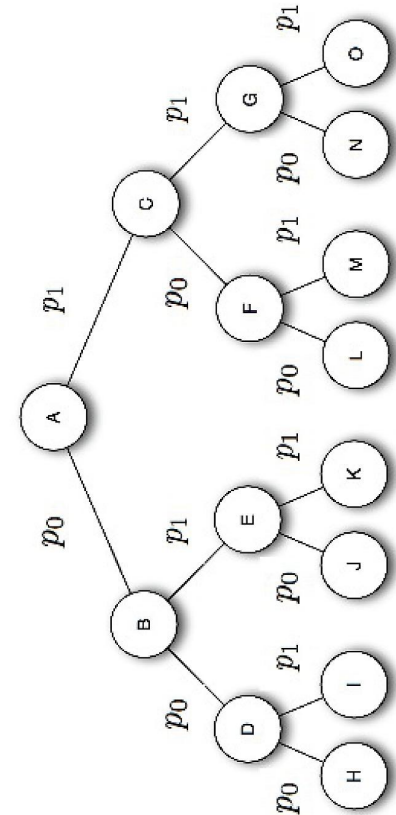
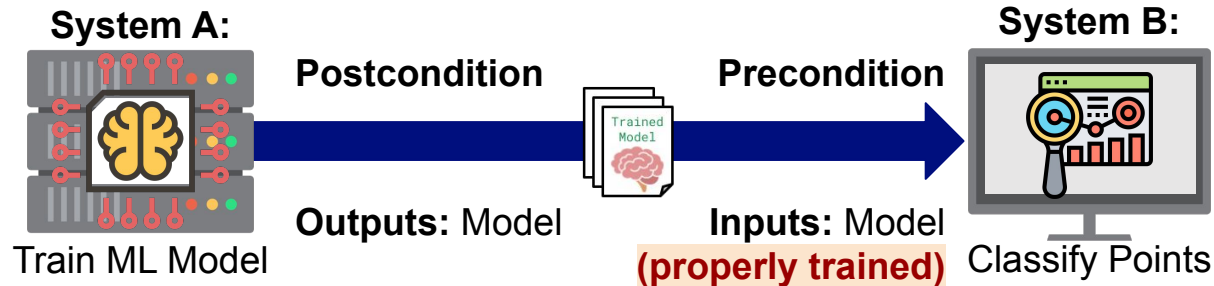
Challenge: Formally Verifying System Composition

We can use formal methods to verify that systems compose correctly without the possibility of incorrect behavior.

This means exhaustively checking that System A's postconditions agree with System B's preconditions. If so, it is safe to compose.

Normal Setting: Every computational path must be accounted for and checked. Verification cost (time) is **multiplicative** across systems.

$$\text{Cost} = |S_1| * |S_2| * \dots * |S_n|$$



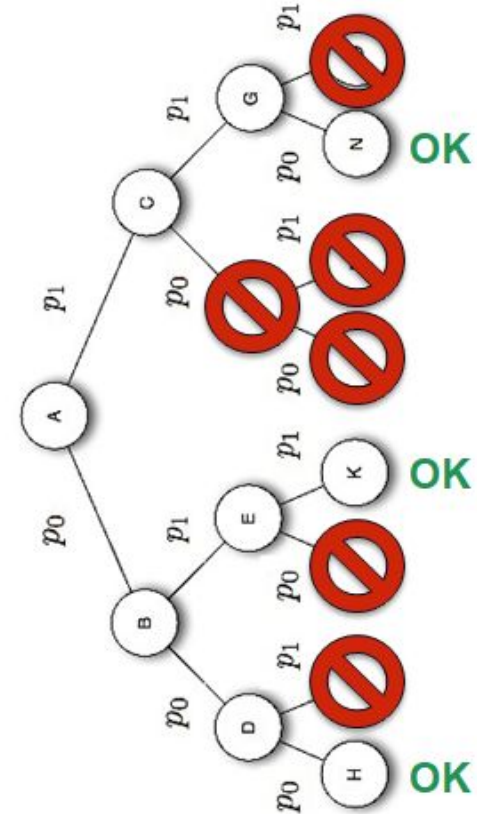
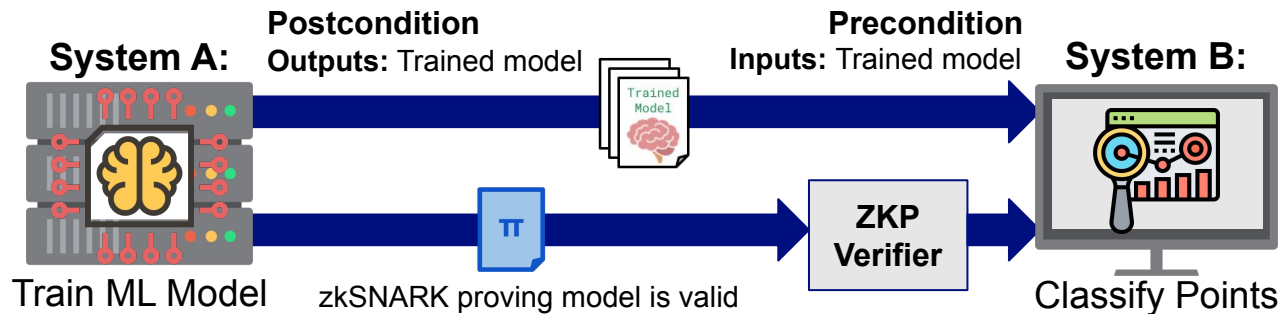
Solution: Assuring Safe Composition via zkSNARKs

Zero-knowledge proofs can be used to provide type checking guarantees of input/output properties without exposing secrets.

Verification can be done modularly so that the cost is **additive**.

$$\text{Cost} = |S_1| + |S_2| + \dots + |S_n|$$

Bad proofs and inputs can still exist, but now are cryptographically (exponentially) hard to find and exploit.



Preconditions and Postconditions with Types

```
Type MLModel =  
  (w : Weights, error(w) < 0.05, log : AuditLog, execute(log) == w)  
trainModel : (x : [Input]) -> MLModel
```



```
classifyPoint : (y : Input, model : MLModel) -> Class
```

We can generate proofs (or an audit log) of desired properties (e.g. functional correctness) and include them with input to other functions.

This allows us to use a dependent type to assure that only models that were actually trained on actual data and are within a certain error threshold can be used by a classifier.

The audit log and its proof would be **huge**. Instead, we can use a super small zkSNARK to prove this dependent type and pass it along instead. We only need to handle the case where the check fails.



Preconditions and Postconditions with Types

```
Type MLModel =                               zkp : ZKP
  (w : Weights, error(w) < 0.05, log : AuditLog, execute(log) == w)
trainModel : (x : [Input]) -> MLModel
```



```
classifyPoint : (y : Input, model : MLModel, verif : ZKPVerifier) -> IO Class
```

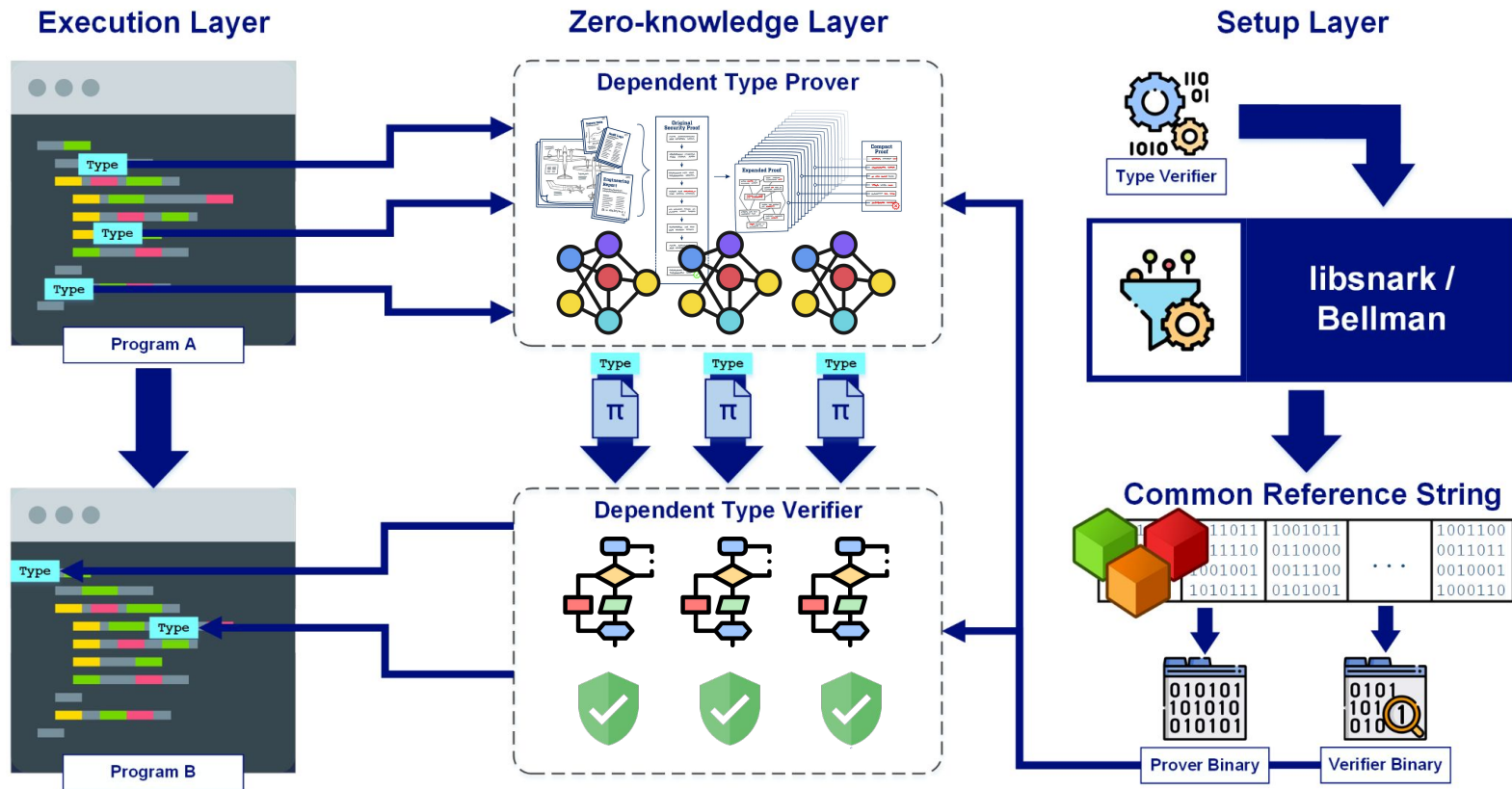
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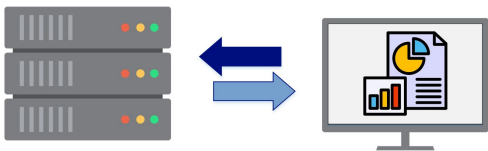


Dependent Type Replacement by ZKPs

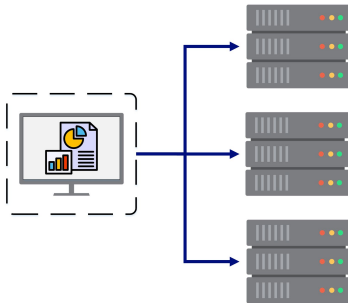


Benefit & Capability

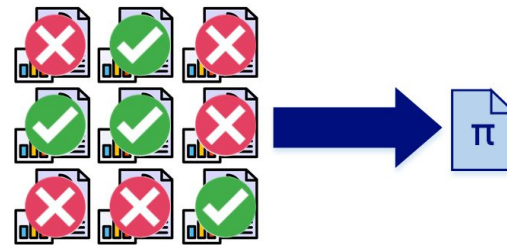
Using zero-knowledge proofs we can combine systems while preventing certain incorrect behaviors relating to mismatched outputs and input constraints.



ZKPs enforce system compatibility without the expense of manually proving correctness



Portable proofs artificially extends our trusted computing base beyond just our own system



ZKPs give fine-grained control over which bits of information to keep secret and which to prove

Project Roadmap

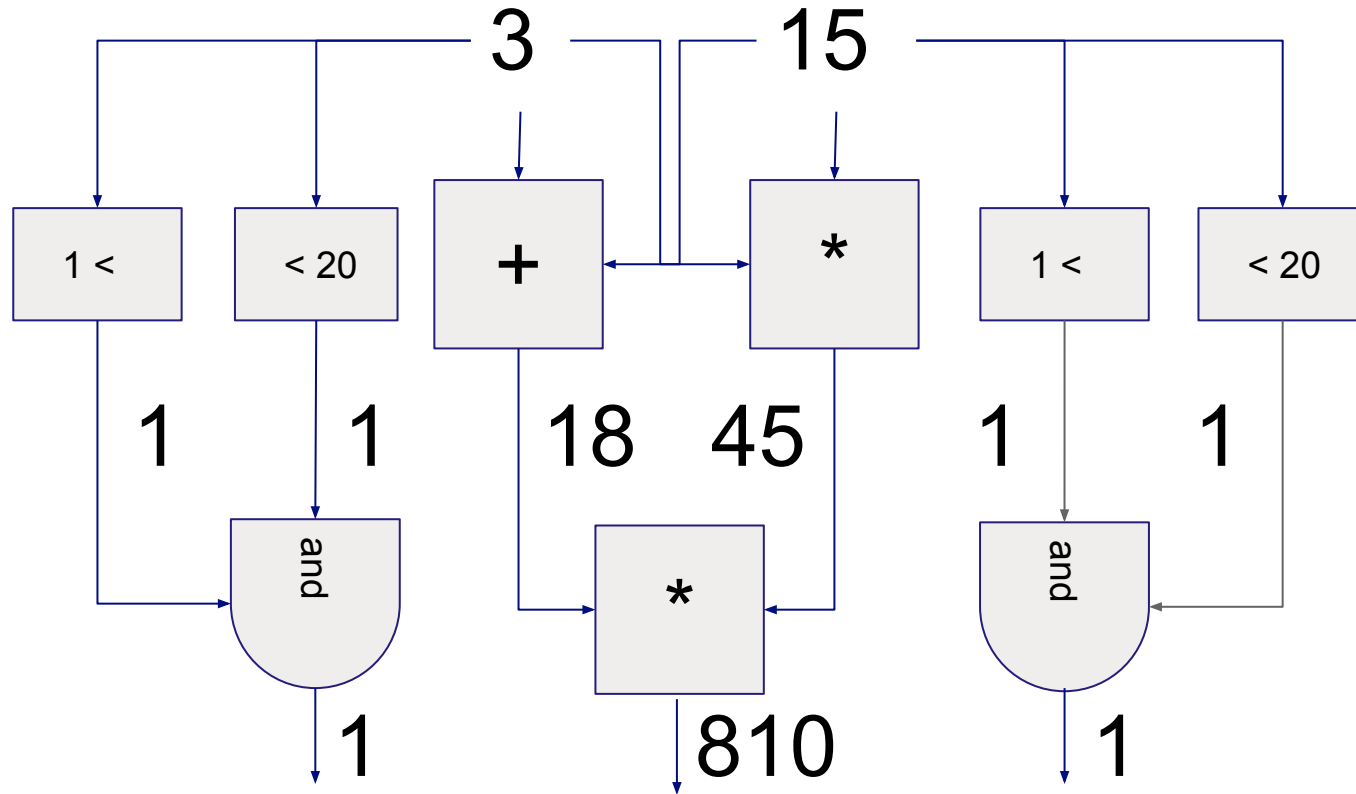
1. Prototype and test program interoperability
 - Manually implement skeleton code in place of zero-knowledge proofs to interact with example program
2. Implement constraint related ZKP gadgets
 - Constraints capture type information that is immediately useful to the test program
3. Develop and set up prototype demonstrations
 - Replace skeleton code with handcrafted ZKP gadgets
 - Develop prototype compiler to read type annotations from file and generate constraints
4. Benchmark and Evaluate



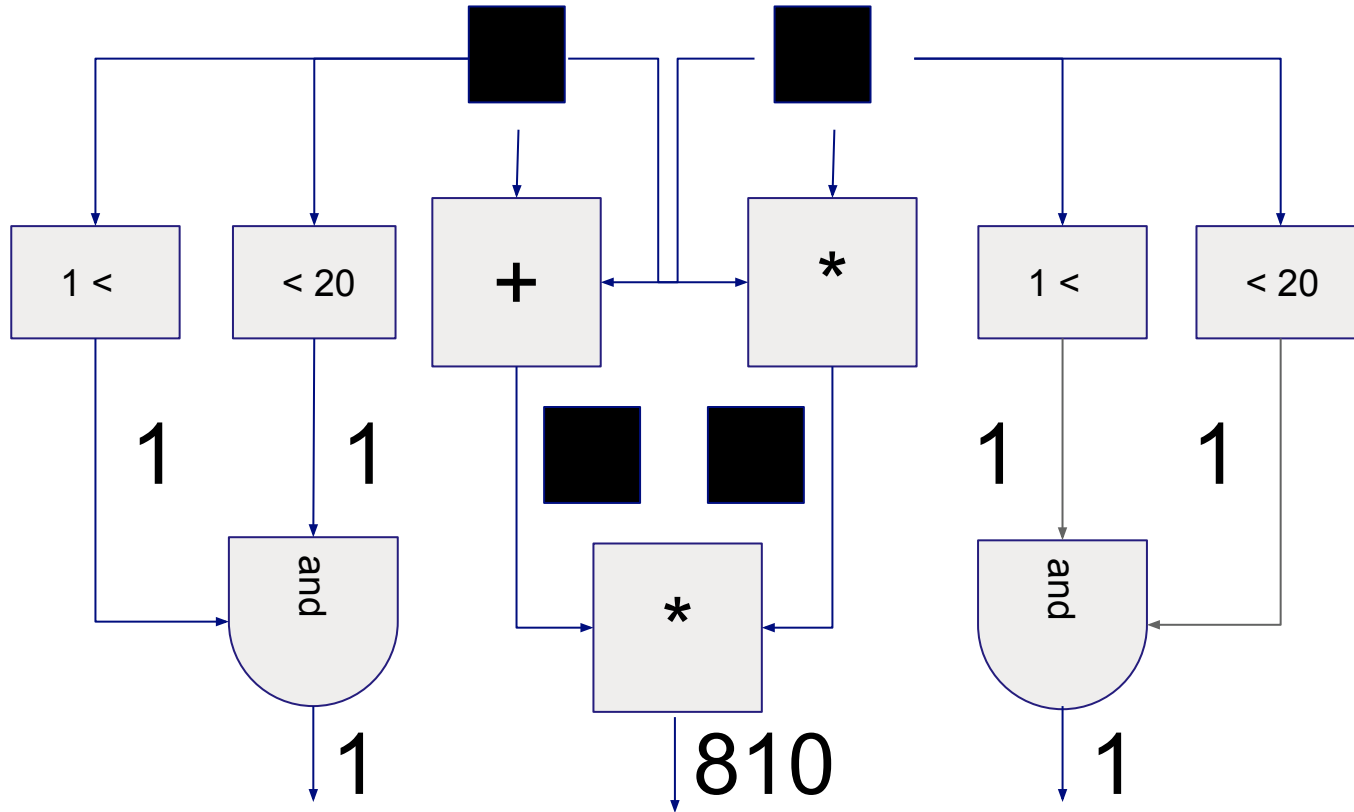
Backup



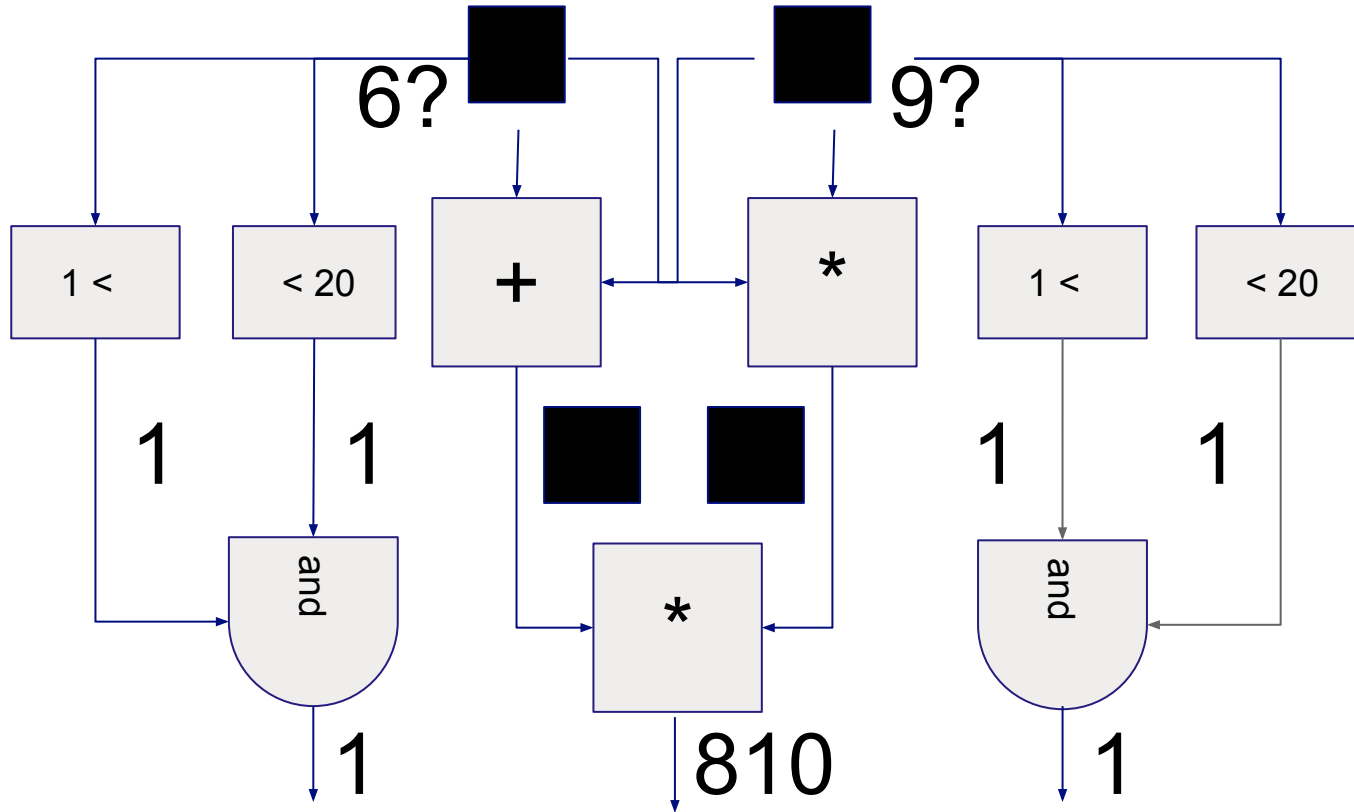
Our function as a circuit



A redacted circuit with zkSNARKs



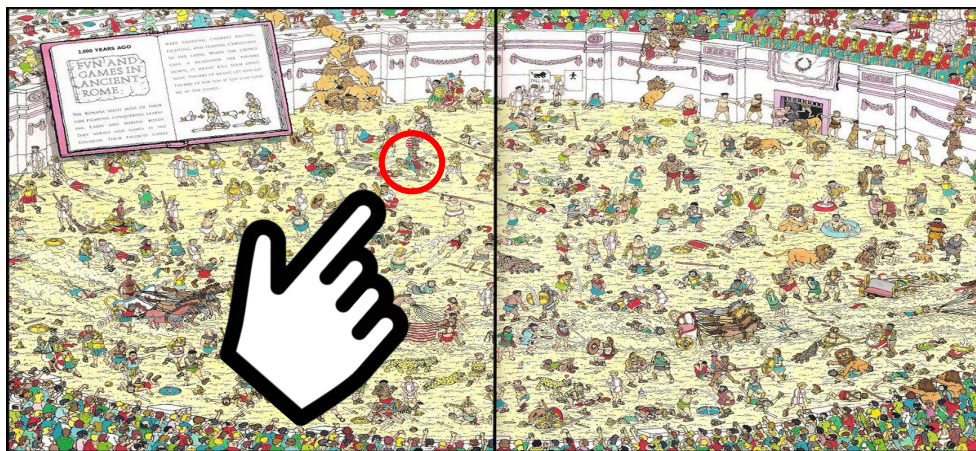
A redacted circuit with zkSNARKs



Zero-Knowledge Proof for *Where's Waldo?*

Example. You want to prove that you have beaten *Where's Waldo?*

- **Traditional Proof:** Point to Waldo to demonstrate you know where he is



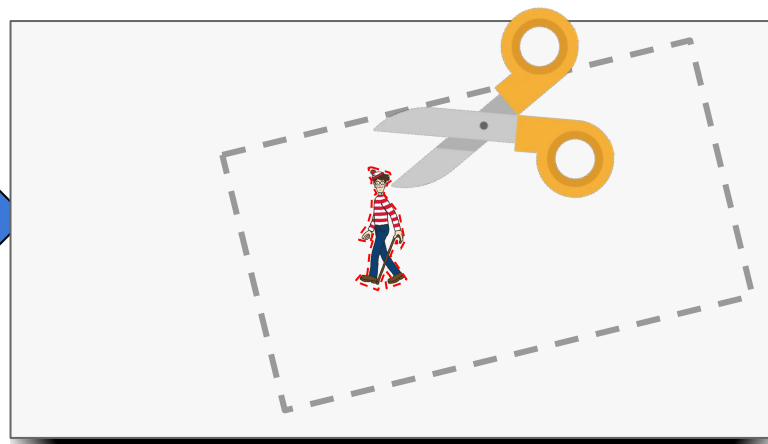
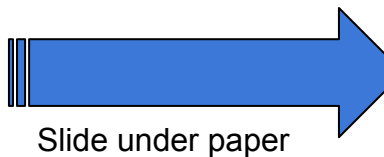
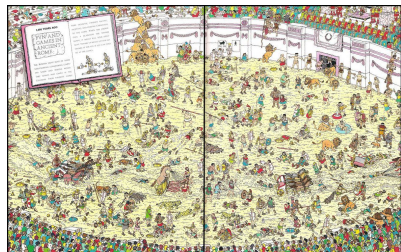
- Not zero-knowledge!

This kind of proof leaks all information about his location, much more than simply that you have *knowledge* of the location

Zero-Knowledge Proof for *Where's Waldo?*

Zero-knowledge proof for “Where’s Waldo?”

1. Cut out a Waldo shaped hole in a much larger piece of paper
2. Position the hole over Waldo’s location



This precisely obfuscates Waldo’s location while demonstrating knowledge of his whereabouts!

To adversaries, the book underneath could hypothetically be in any random orientation

Completeness vs. Soundness

Typical proof systems have 100% completeness and 100% soundness

Completeness: $\mathbb{P}[\text{true statement AND verifier accepts}] = 1$
“Everything true is provable”

Soundness: $\mathbb{P}[\text{false statement AND verifier rejects}] = 1$
“False statements aren’t provable”



Cryptographic Proof Systems

Cryptographic proof systems have variable completeness and soundness. For non-interactive zero-knowledge proofs we care about:

(Completeness) $\mathbb{P}[\text{true statement AND verifier accepts}] = 1$
“Everything true is provable”

(Soundness) $\mathbb{P}[\text{false statement AND verifier rejects}] = 1 - \epsilon$
“Low chance that a proof of a false statement is encountered”

We sacrifice minimal amount of soundness (have to break crypto to produce counter-example) in order to get valuable proof properties

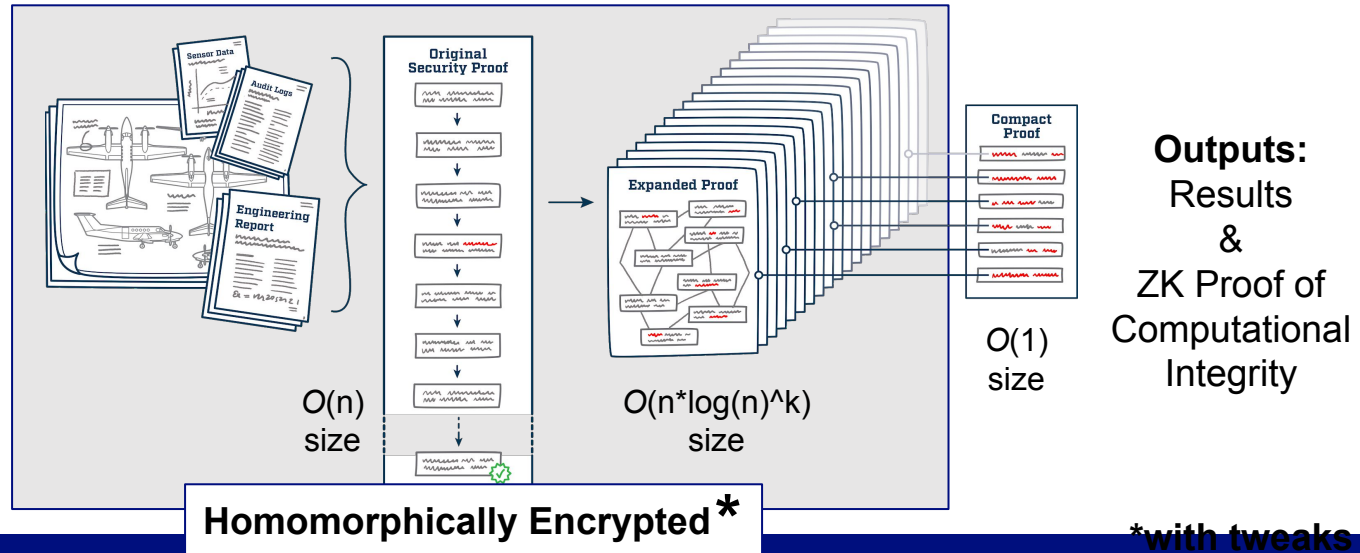


Zero-Knowledge Proofs and Verifiable Computation

Zero-knowledge proofs (ZKPs) allow us to prove that a claim **IS** true without revealing **WHY** it is true, even if the prover is untrusted and malicious.

zkSNARKs are special ZKPs that are *tiny* and *non-interactive*

Inputs:
Logs
Schematics
Program Traces
Signals
Encryption Keys
Attestations
etc.



zkSNARK Construction for Program Verification [BCGTV13]

```
int myFunction(int a) {  
  int b=a*a-4;  
  return 3*b+a;  
}
```

Rank-1 Constraint System (R1CS):

$S \cdot A$		*	$S \cdot B$		=	$S \cdot C$	
1	0		1	0		1	0
a	1		a	1		a	1
t0	0		t0	0		t0	0
b	0		b	0		b	0

libsnaark

Computation

Arithmetic
Circuit

R1CS

QAP

LPCP

LIP

zkSNARK

Proof Representation
Of Program Execution

Zero Knowledge Added

Succinctness Added

Interactivity Removed

libsnaark
backend

Verifier
Binary

Prover
Binary



zkSNARK for
Program Integrity



Theory Behind ZKPs (Backup)



PCPs & Hardness of Approximation

Intuition

Efficient approximation scheme for a problem implies that it is easy to create a good enough looking “fake” solution (witness)

So,

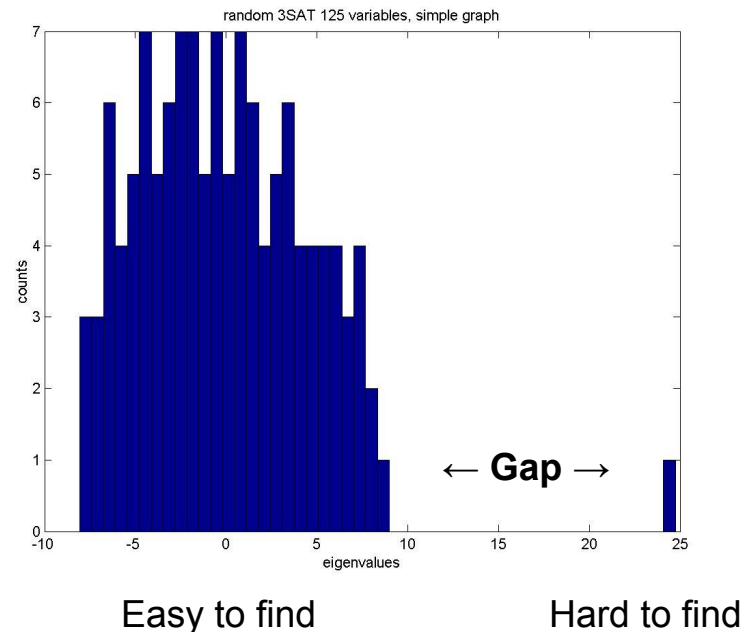
Hard to approximate



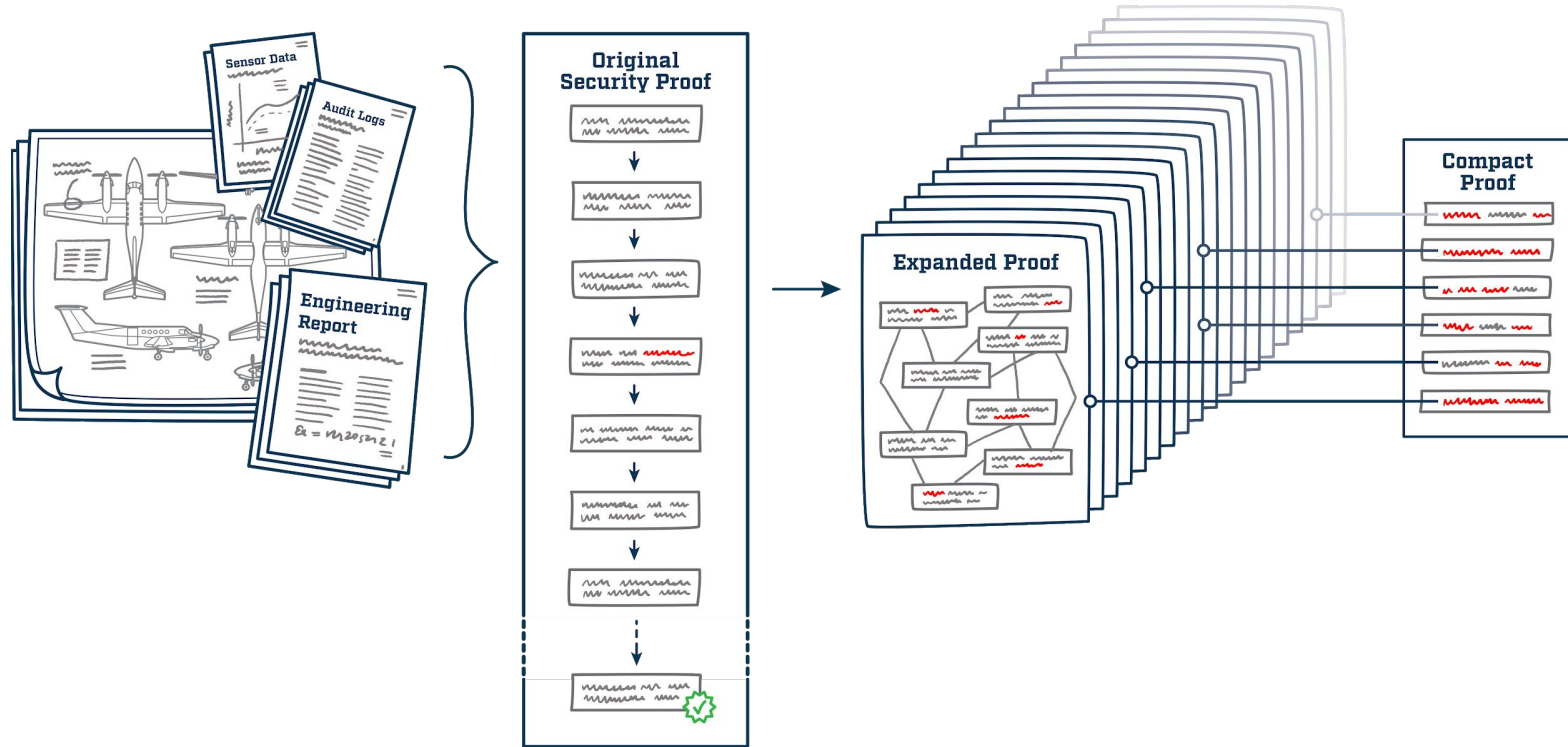
Hard to create a convincing fake witness that appears optimal



Good witnesses imply that best solutions exist



NIZK Overview

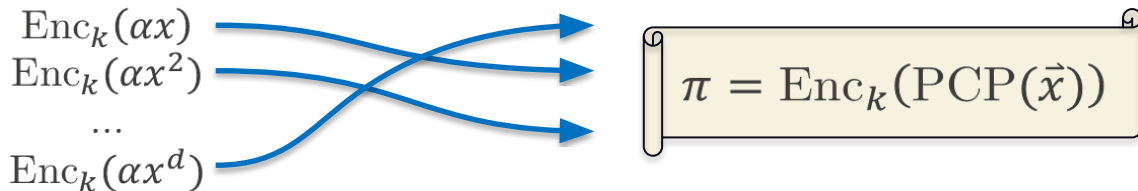


Circuit Evaluation

1. Publish homomorphically encrypted building blocks for a program

$$\text{CRS} = \{\text{Enc}_k(\alpha x), \text{Enc}_k(\alpha x^2), \dots, \text{Enc}_k(\alpha x^d)\}$$

2. Prover blindly re-assembles them to compute the desired circuit (e.g. an evaluation of the PCP circuit) and adding random blinds where appropriate



3. Verifier checks content by simply decrypting

$$\text{Dec}_k(\text{Enc}_k(\text{PCP}(\vec{x}))) = \begin{cases} 1 & \text{if valid} \\ 0 & \text{if invalid} \end{cases}$$